State, Context, Adaptability, and Scale for Self-Learning Closed Loop Policies

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Quality Attributes for a Policy Framework

The Attributes

- State: Keep track of where we are and what we're doing
- Context: Keep track of what's going on around us
- Adaptability: Able to be changed and to change in response to where we are, what we're doing, and what's going around us

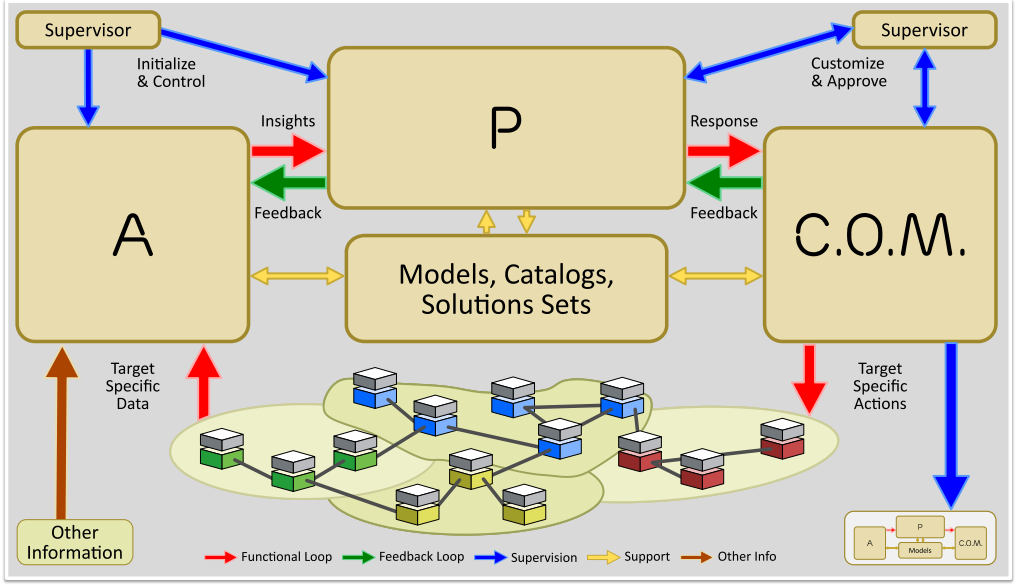
Whilst allowing

- Scale: The ability to do the three bullets above while increasing and decreasing our capacity depending on the load

With the ultimate goal of

- Self-learning: Harnessing and governing machine learning to provide learnt policies

Policy for Closed Loops, Work since 2012

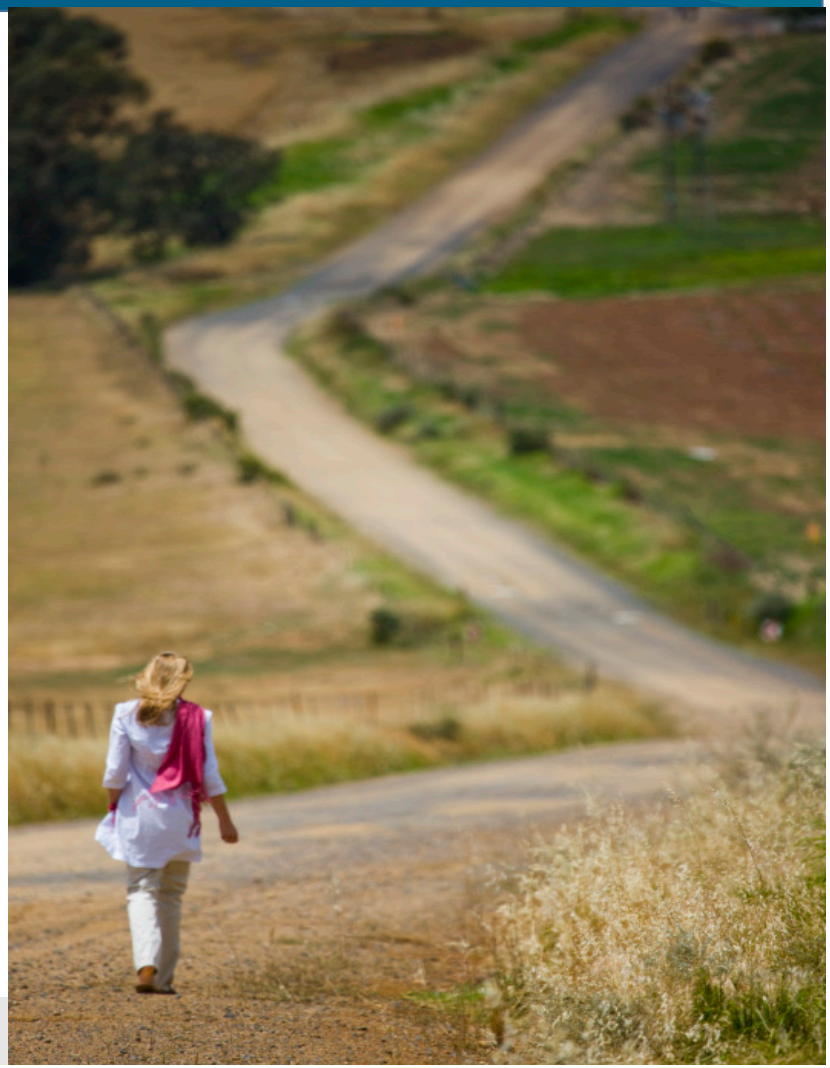


COMPA, a reference architecture for closed loops

Control, Orchestration, Management, Policy, Analytics

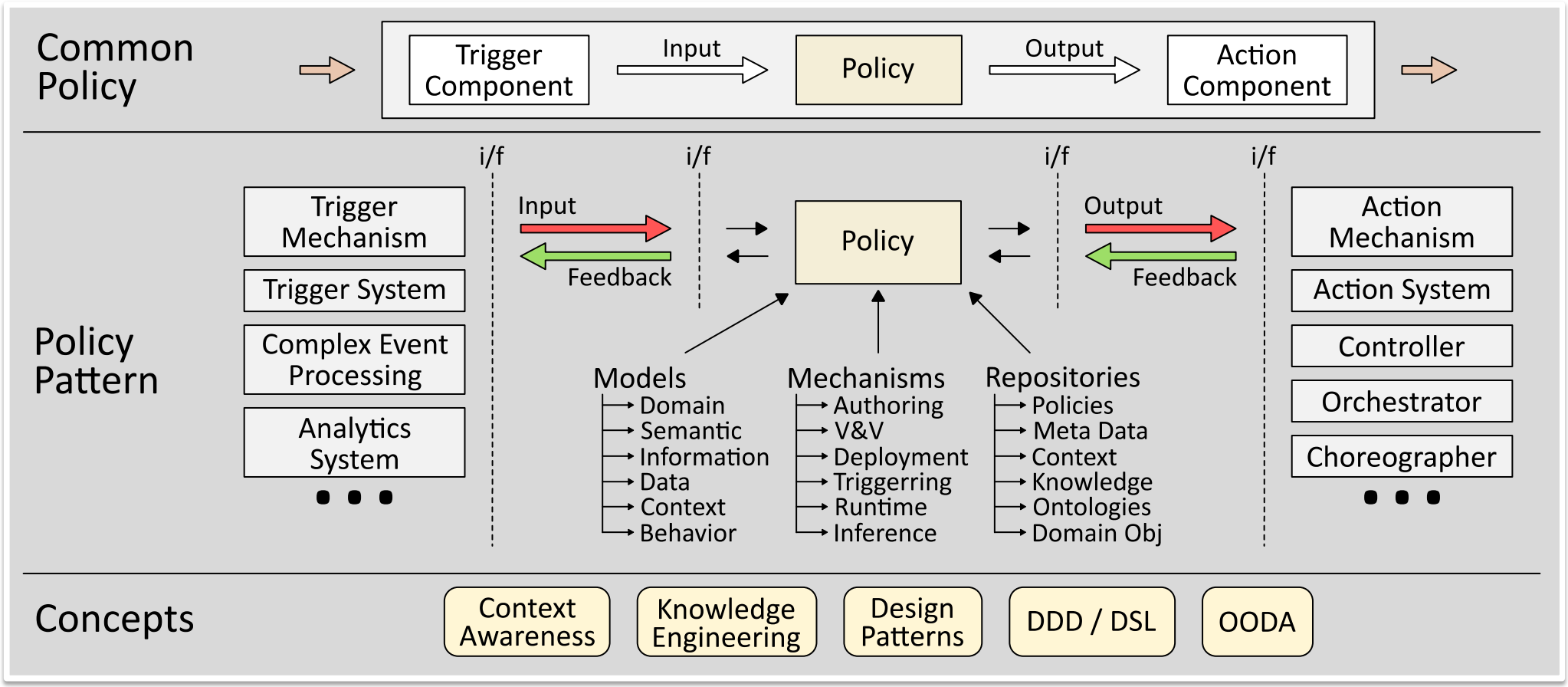
- Analytics, Control and Orchestration becoming complex
- Policies in Control Loops were static, unstructured, and in silos
- Policy Program
  - Established well founded theory for policy in Closed Loops
  - Developed a pre-production policy system to apply that theory in practice

UNIFIED POLICY THEORY (UPT) PRIMER

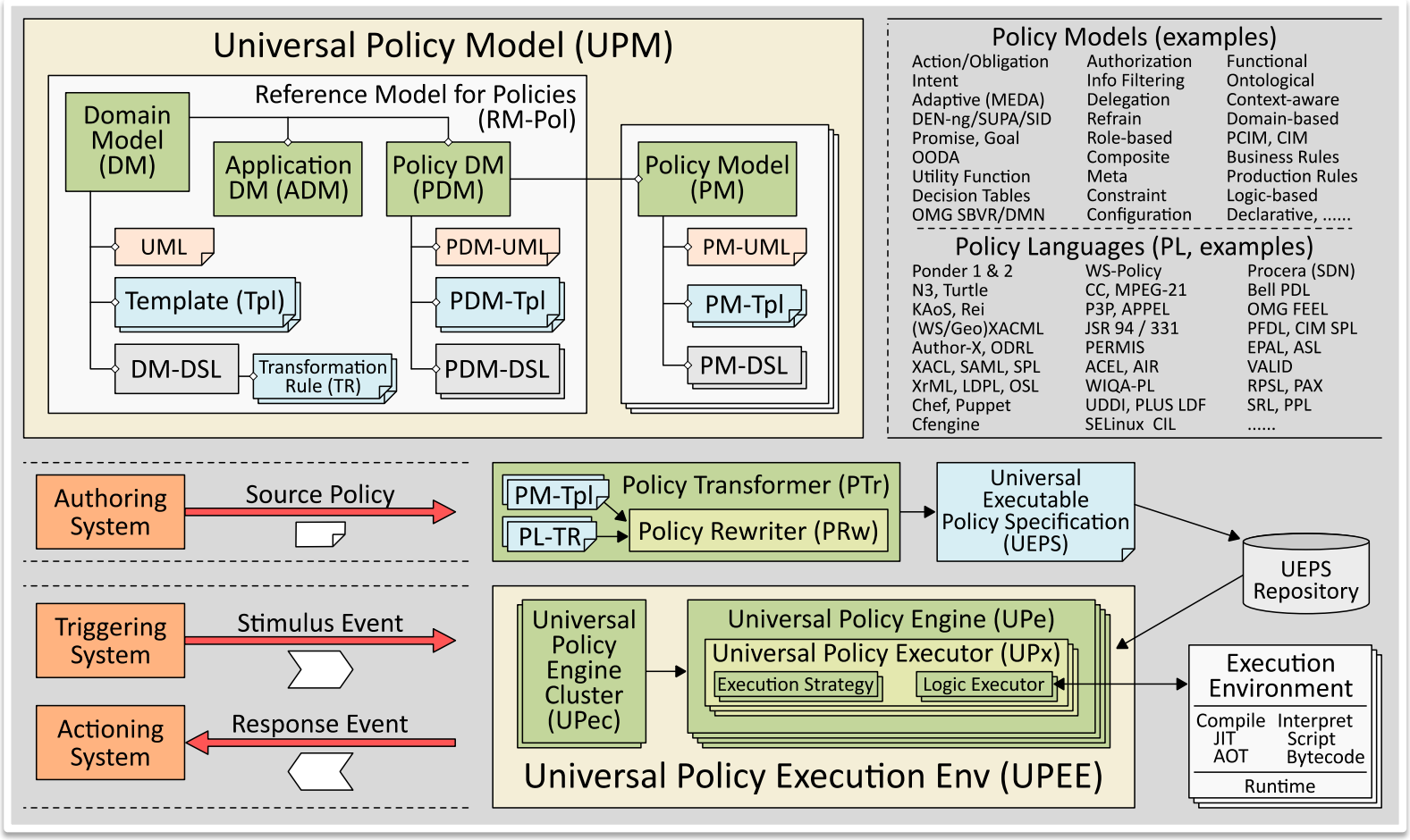


For full details on Unified Policy Theory, see our research papers in the APEX project in ResearchGate

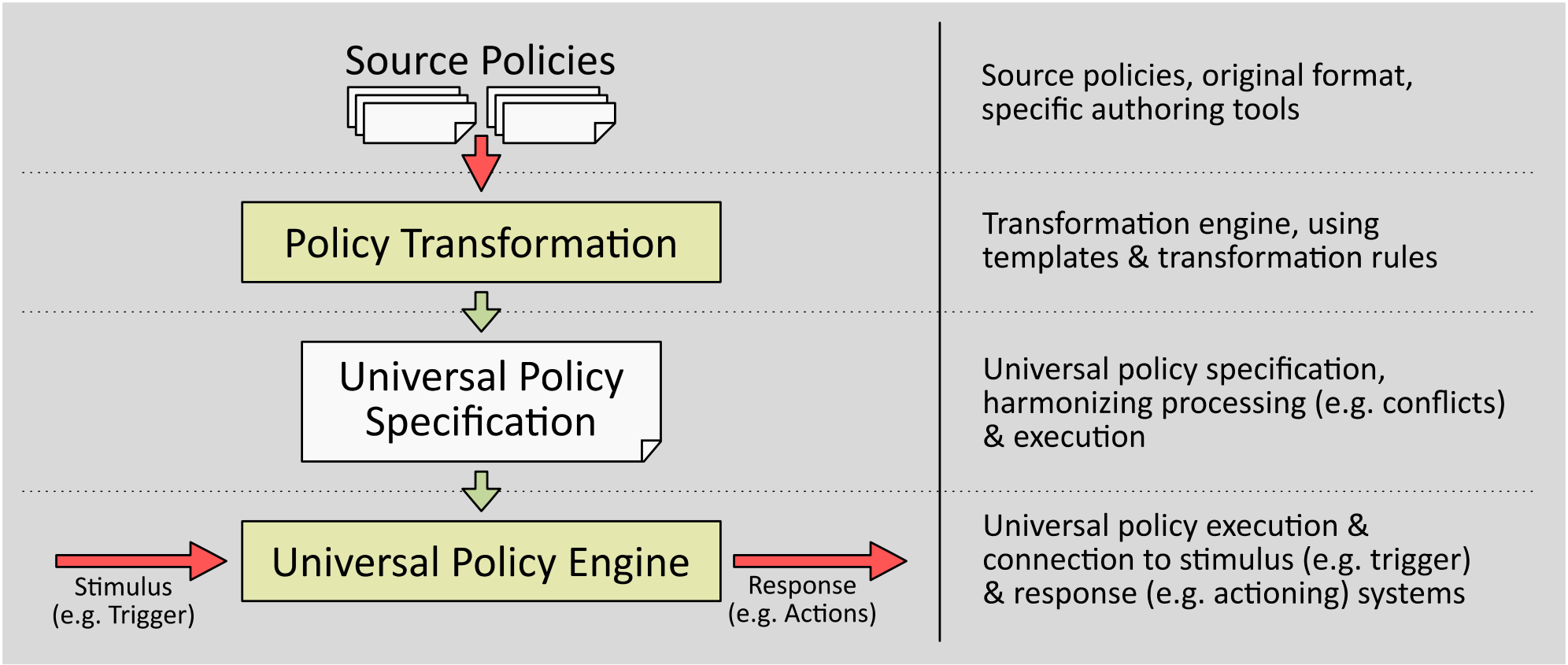
Policy Patterns and Roles



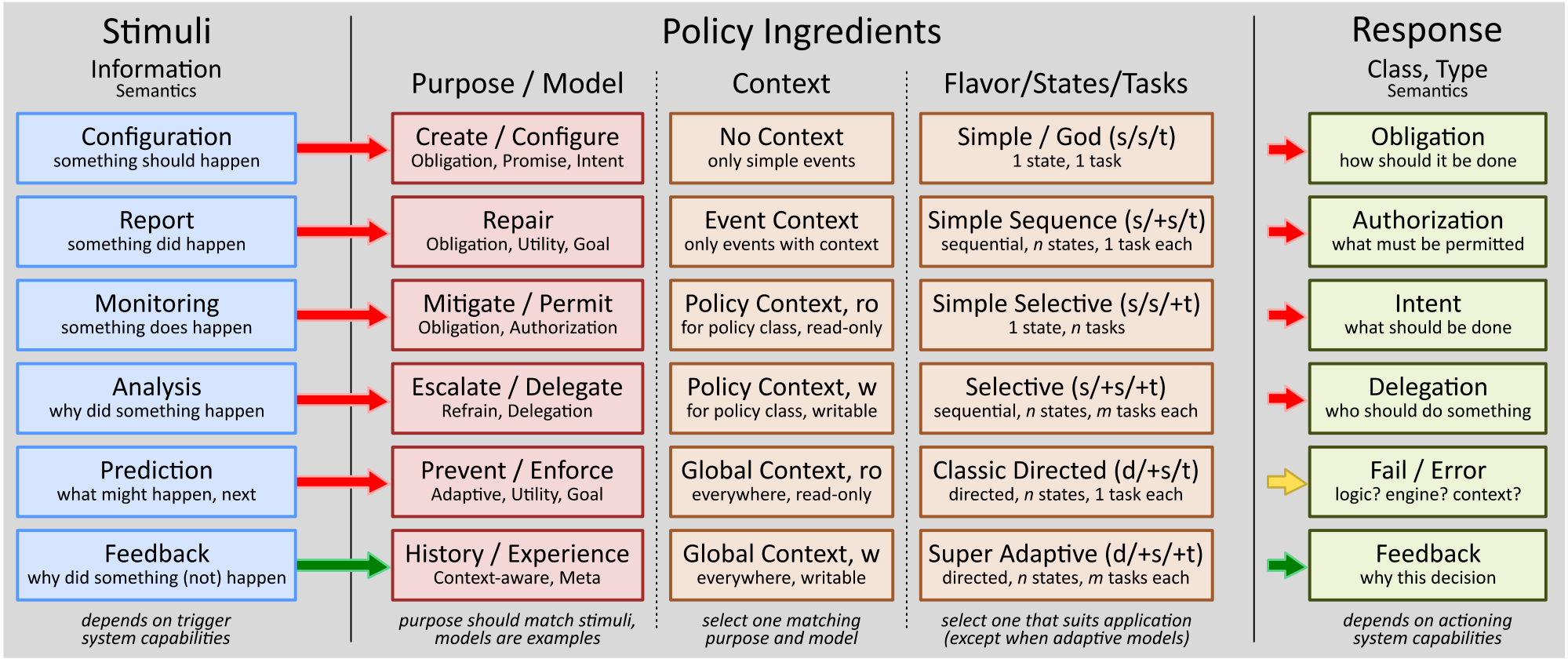
Unified Policy Model



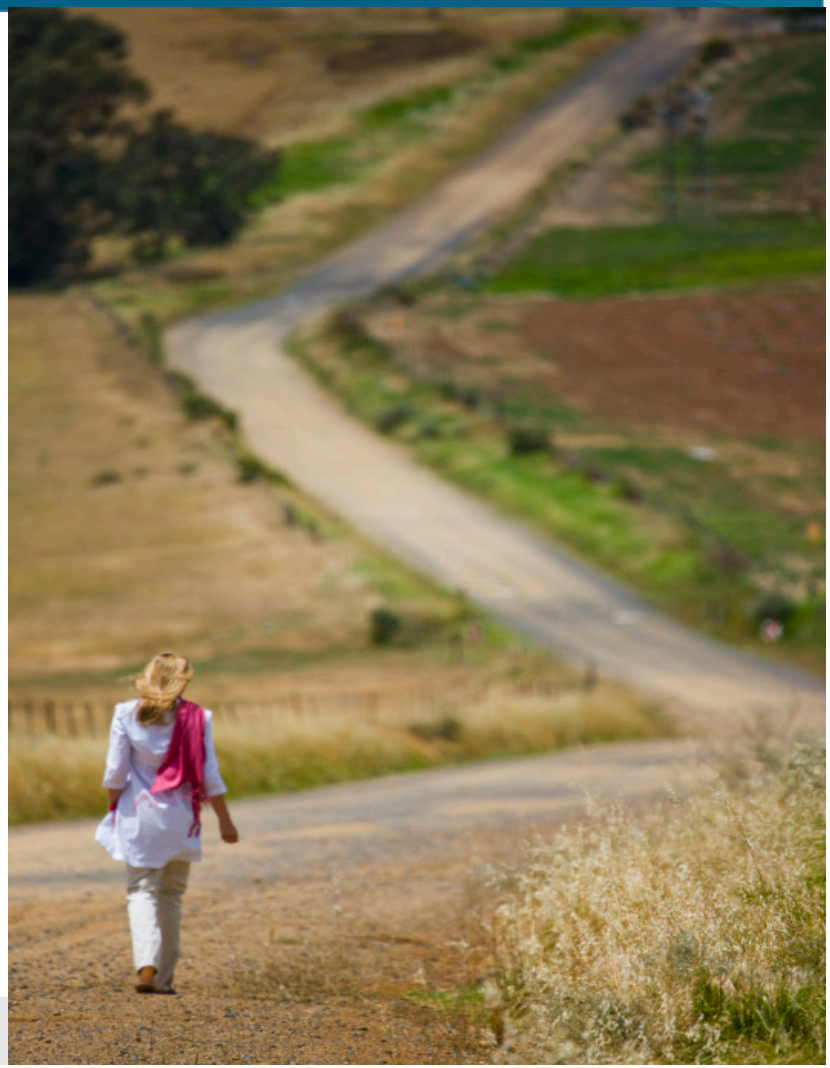
Policy Transformations



Policy Matrix



APPLYING UNIFIED POLICY THEORY IN A SYSTEM



Concept & Implementation

Theory

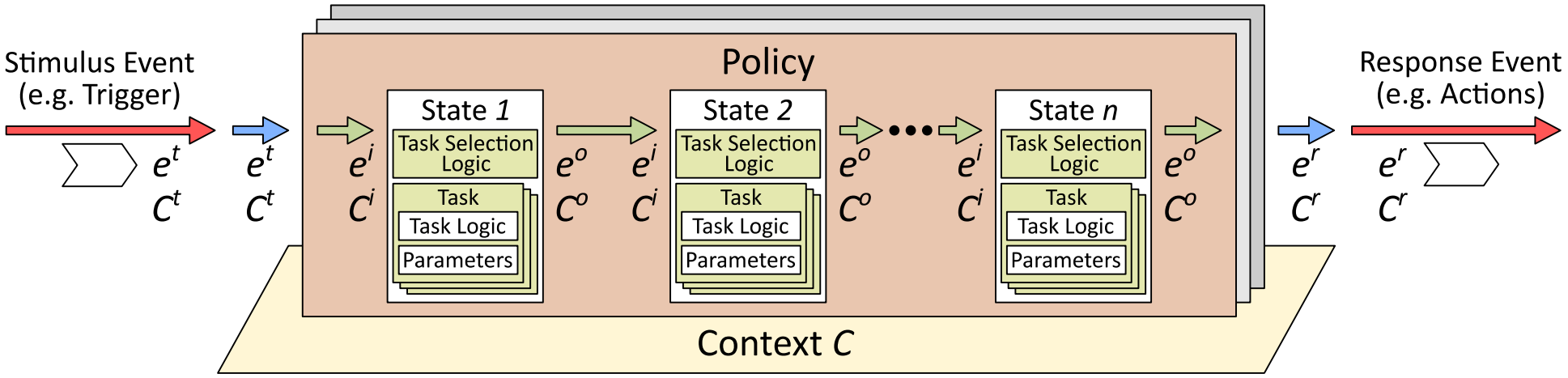
- Harmonize policy models
- Provide single execution environment
- Facilitate conflict processing
- Features
  - Context aware
  - Adaptive logic selection
  - Flexible clustering options
  - Flexible deployment options
  - Flexible policy deployment

Practice

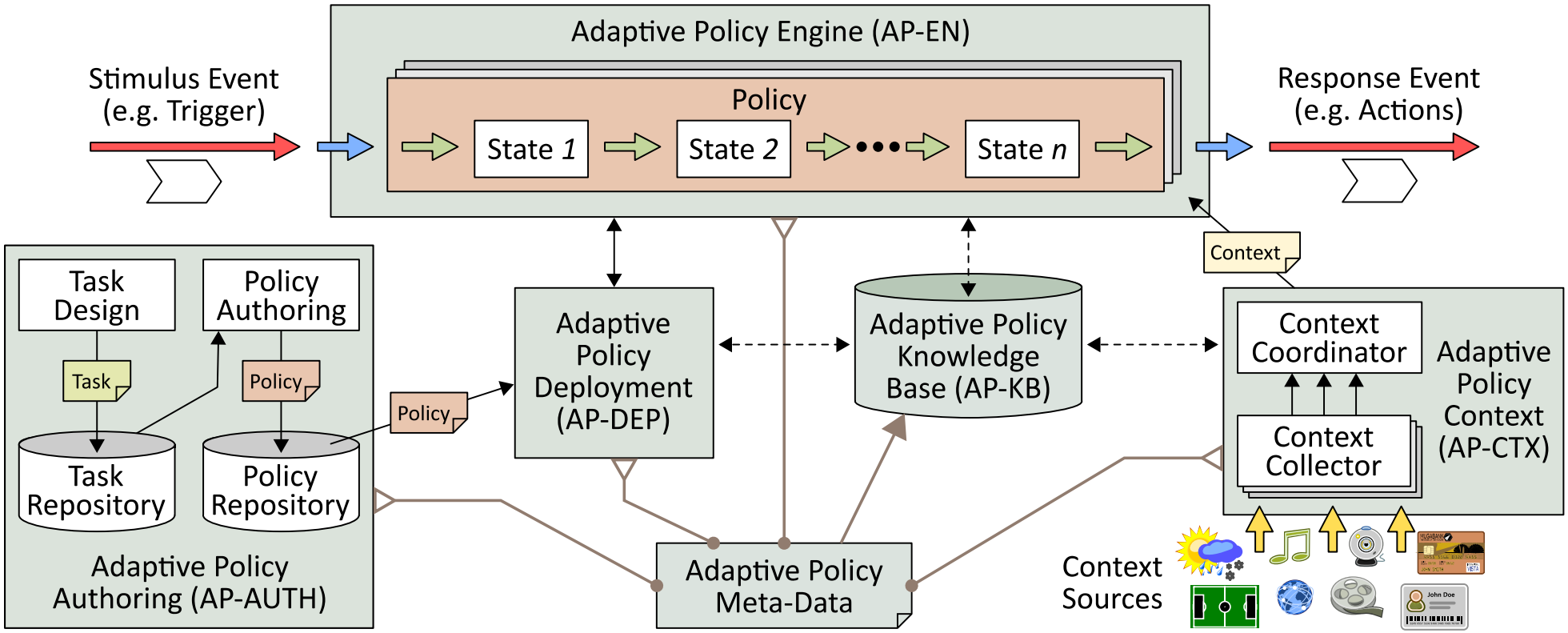
- An editor to create policy models
- An engine to run policy models
- Control of state and context
- Features
  - Context defined at run time using metadata
  - Logic loaded at run time
  - Policy Deployed as metadata
  - Policies/context distributed for scale

Adaptive Policy Engine: Event Flow & Context

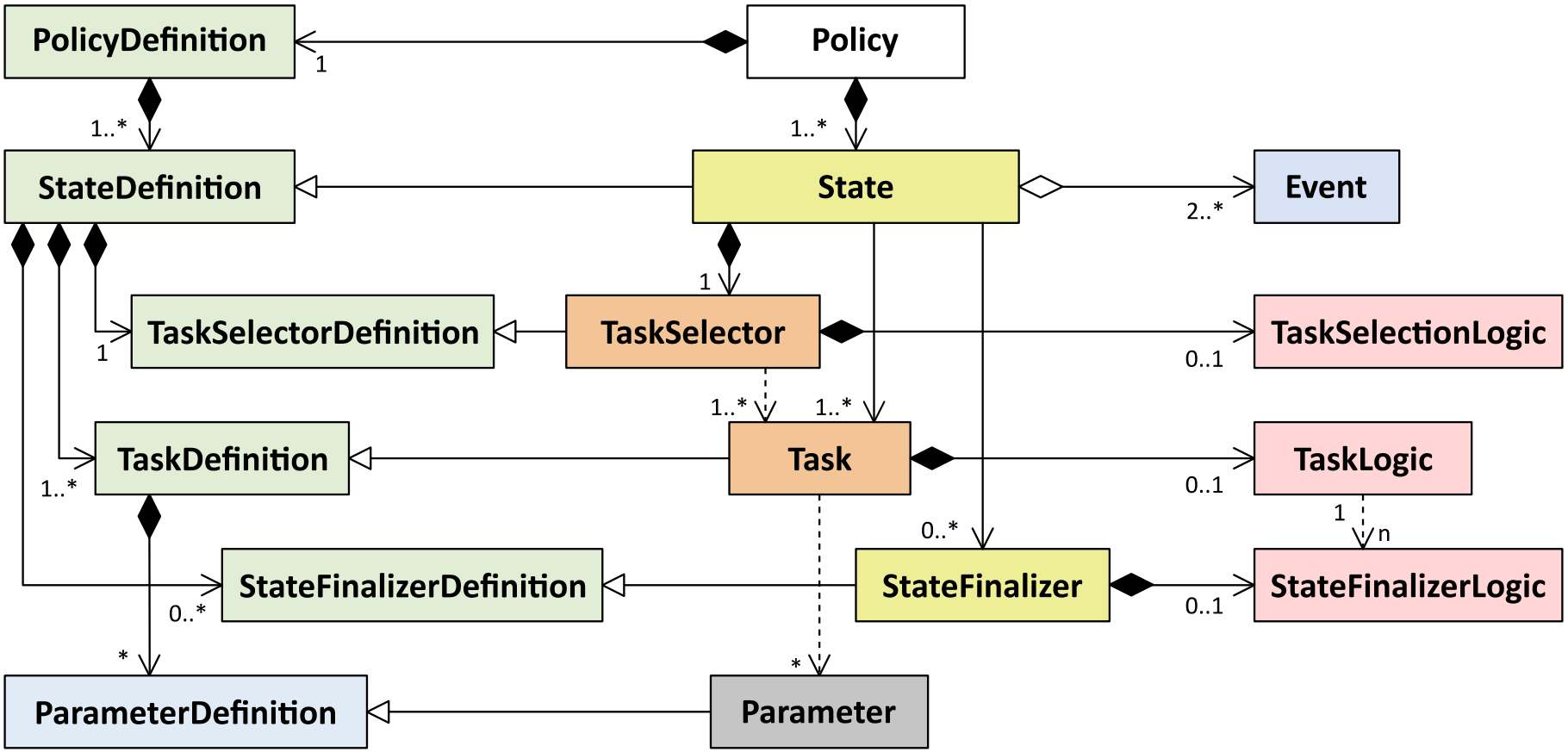
- Flow: Trigger → Engine → Policy → Engine → Actioning System
- Context: in all events, per policy type, global (r/w), external (r)



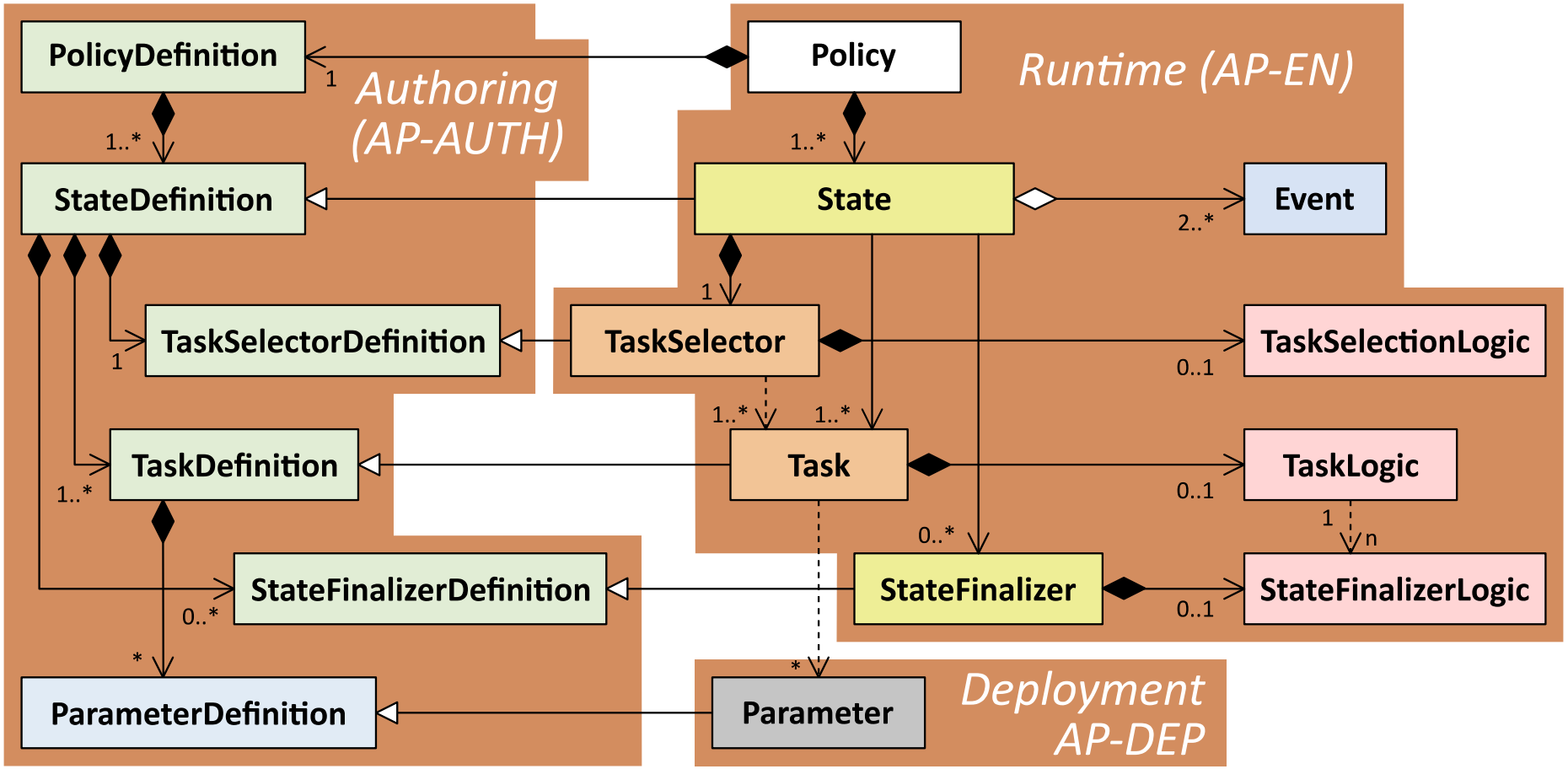
Policy Environment Components & Flow



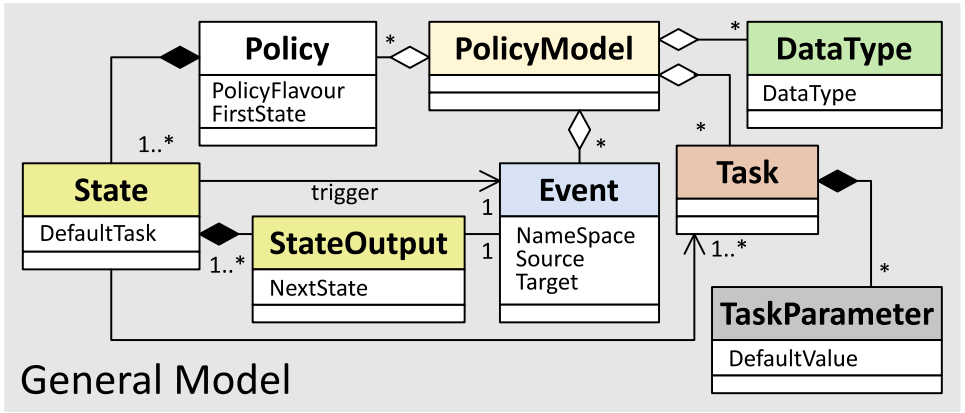
The Universal Policy Theory (UPT) Policy Model as UML

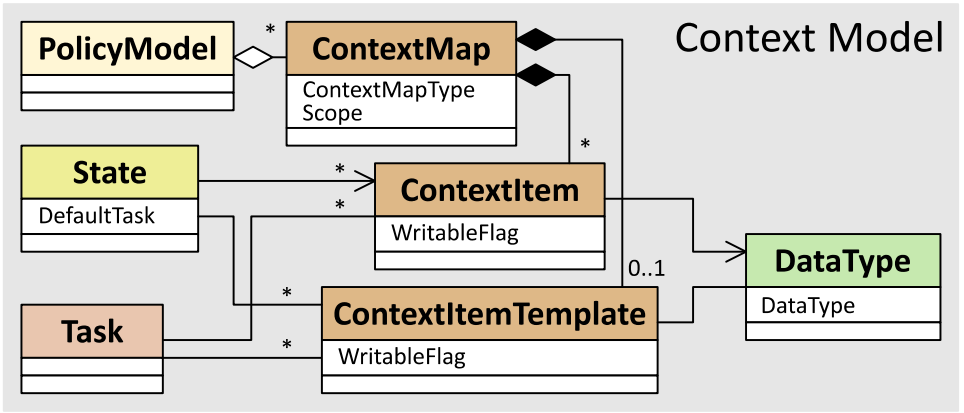


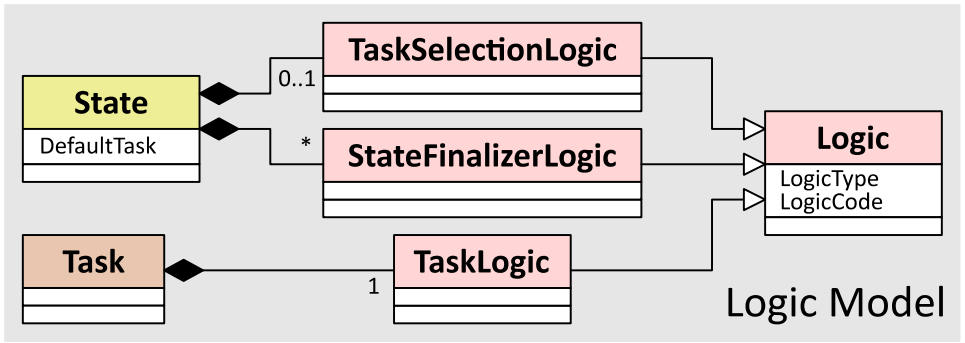
The UPT Policy Model mapped to a Policy System

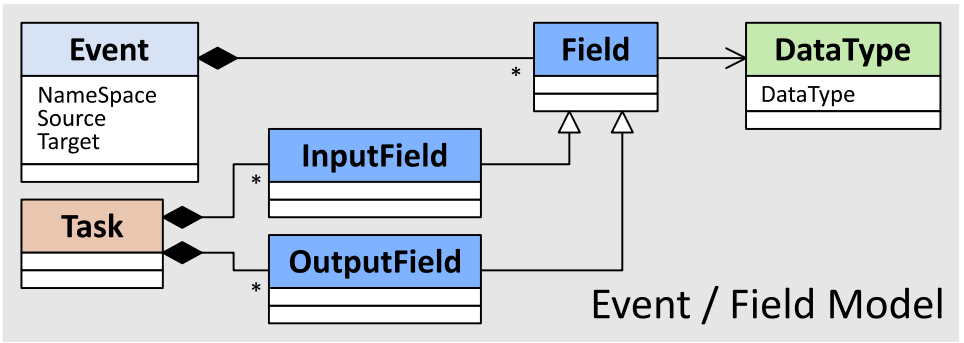


Engine Execution Model

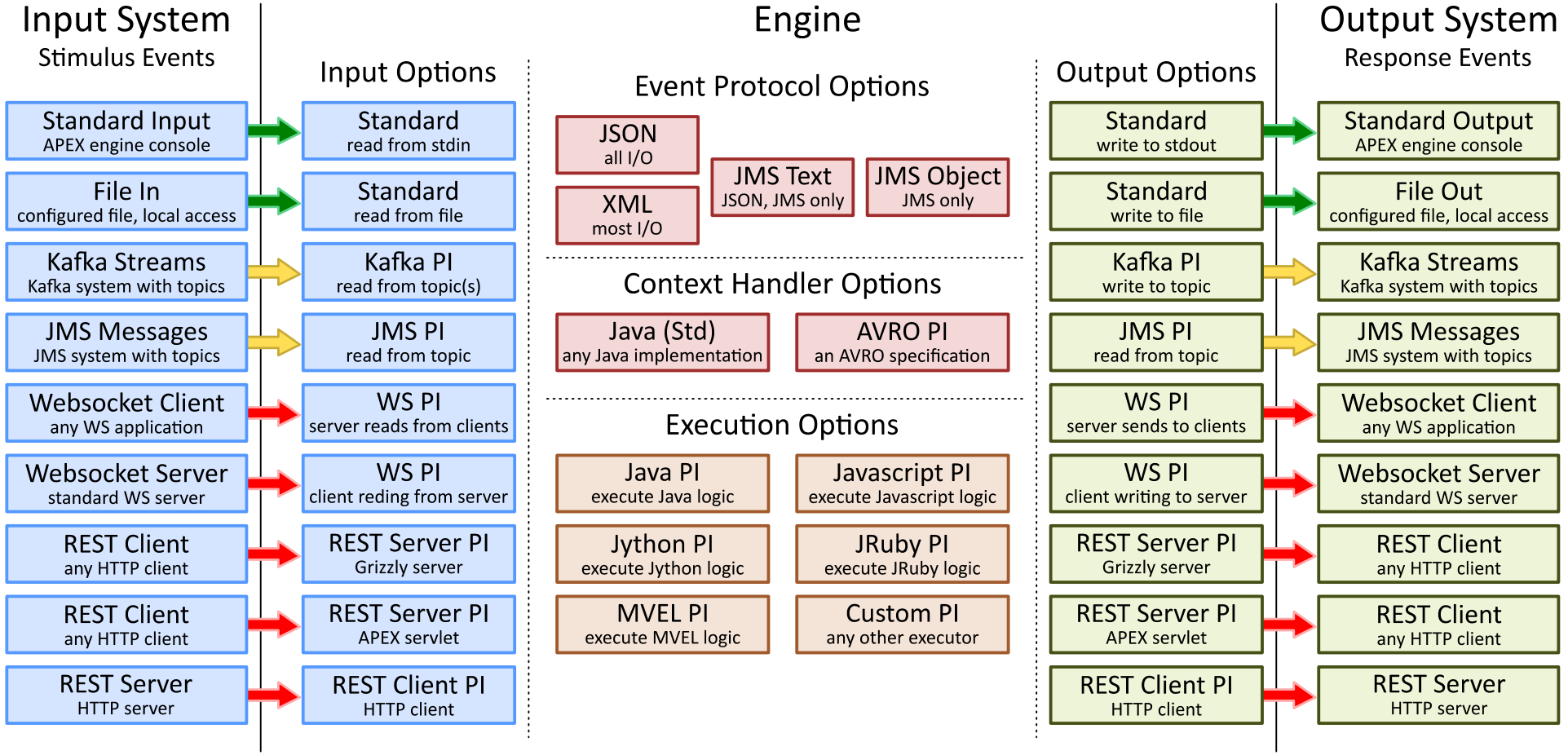




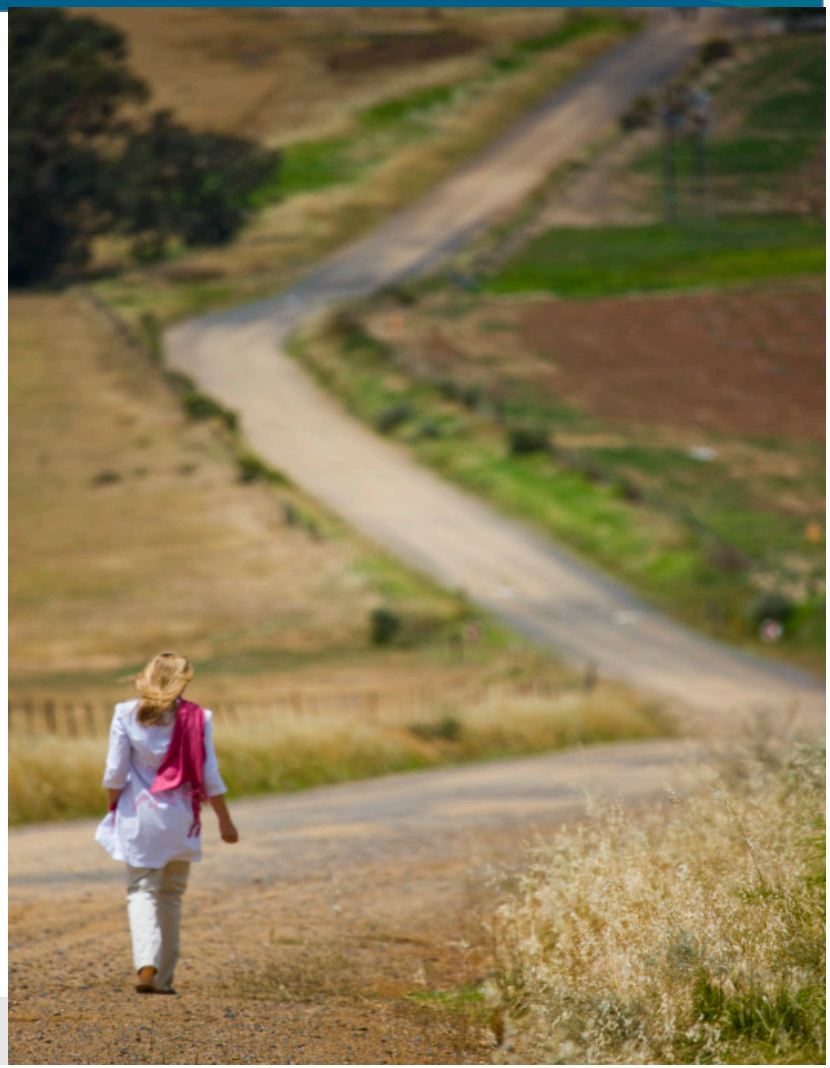




Engine Configuration and Plugins



DISTRIBUTED CONTEXT FOR POLICY



Distributed Context for Policy

- Policy work required context sharing across policy engines
- We wanted structured context just like what's available in management models
  - Think MIBs, Yang objects, UML classes, Java Beans, XML entities, JSON objects, …
- We went looking for a model distribution system that
  - Provides distributed context (somehow classified information)
  - Supports locking
  - Supports monitoring
  - Supports persisting
- No such distributed context framework existed

Distribution Frameworks

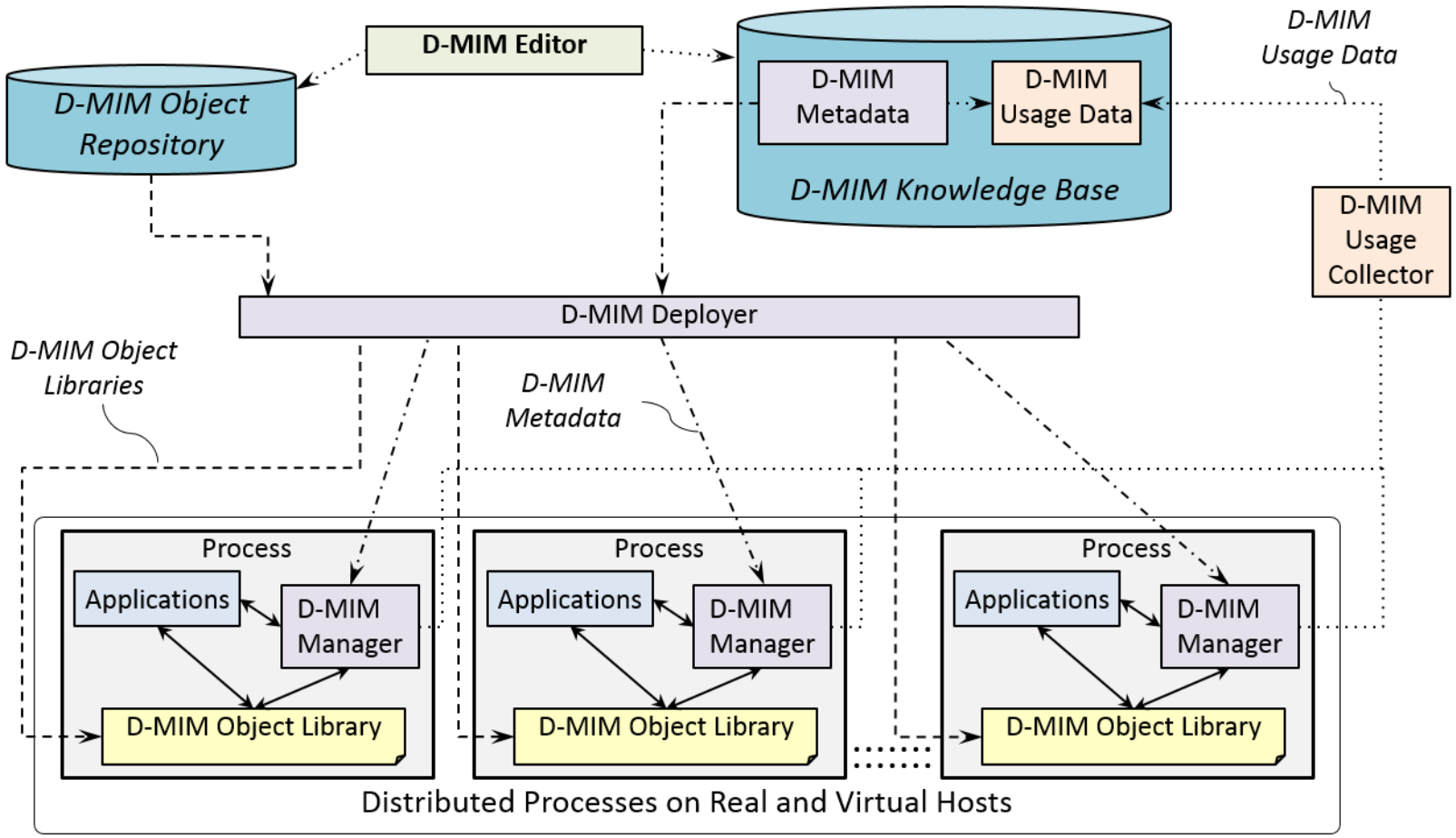
- Numerous frameworks for distributing unstructured hash maps
  - Distribution of maps of objects keyed by objects
  - E.g.: Hazelcast and Infinispan

- Some frameworks for locking
  - Transactional frameworks such as Narayana (Jboss JTA implementation) are slow
    - and very expensive in resource usage
  - No locking support on specific entries on distributed maps
  - No integrated persistence support
  - No integrated monitoring of CRUD operations on map entries

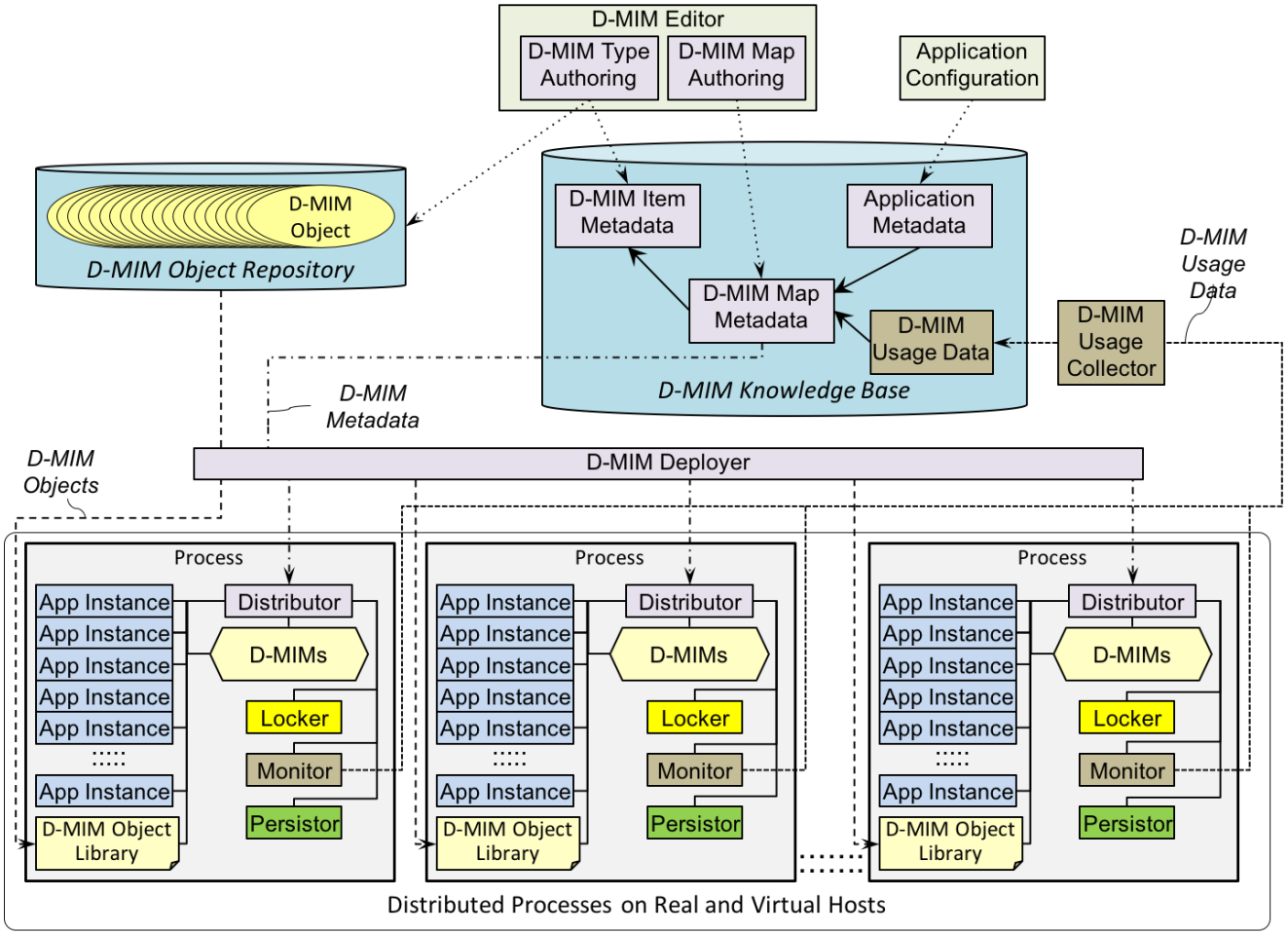
Distributed MIMs

- We decided to build a system for context that had strong structure support (just like MIMs)
  - Provides an interface to users to define highly structured context
  - Provides an interface to users to read, write, create, delete, persist, lock, and monitor context
  - Provides a plug-in architecture that allows existing distribution, locking, persistence and monitoring frameworks to be used
- D-MIM users can use distributed MIM maps
  - transparently on multiple processes, hosts, and geographic locations
  - Changes to one D-MIM copy are propagated to all others
  - Unified monitoring is supported
  - Unified locking is supported

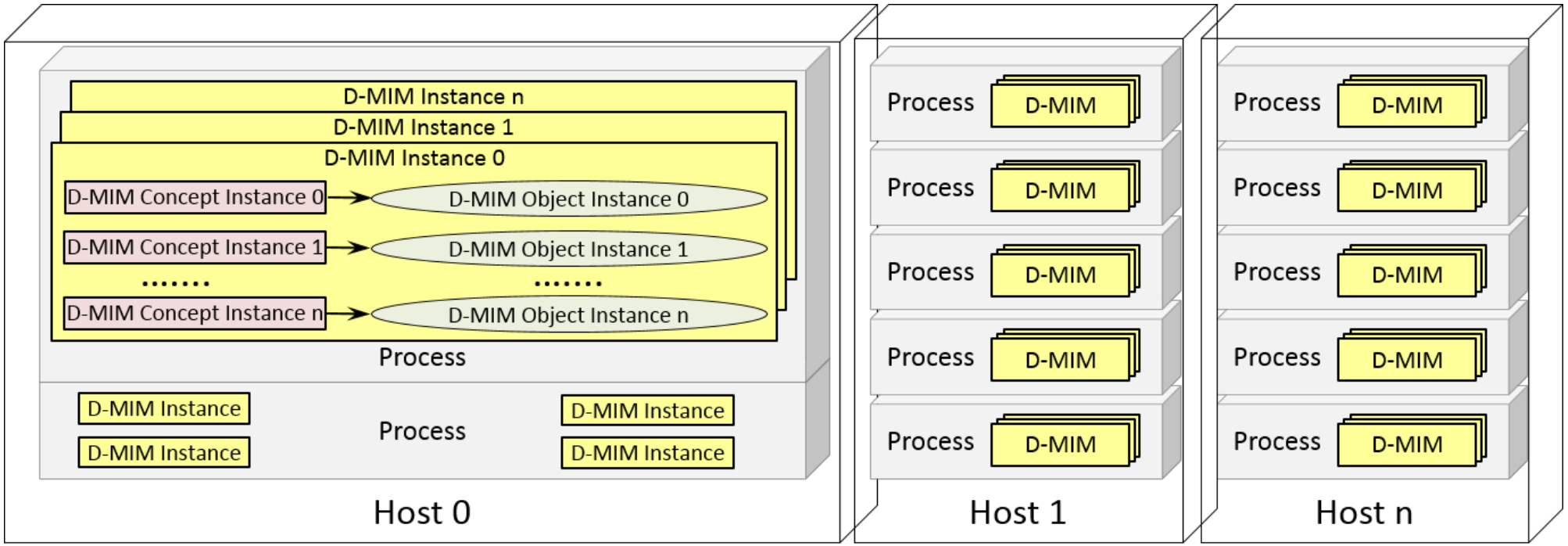
Distributed MIMs (D-MIMs) in Policy Engines



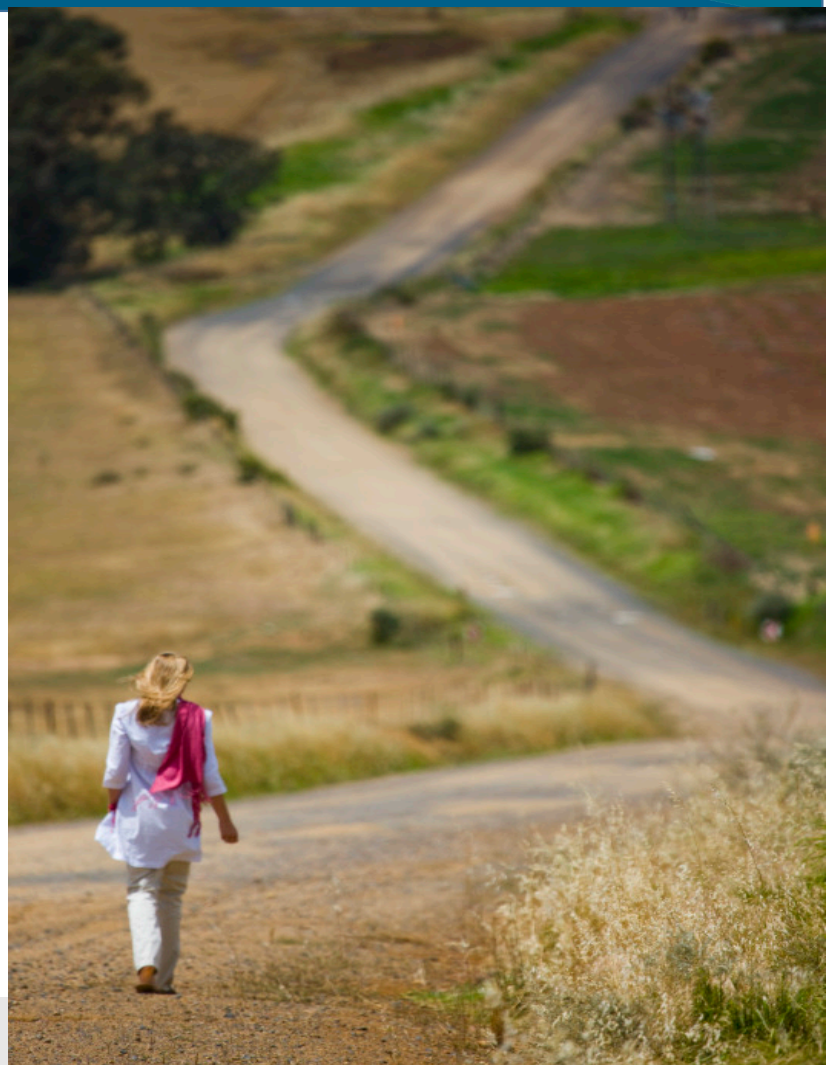
D-MIMs in a Distributed System



Distributed MIM instances on Hosts



APPLYING TO ONAP



UPT and UPEE in ONAP

- A model for policies and policy engines
  - Drools and beyond Drools, state handling
  - XACML engine, stateless
- UPM model distribution using ONAP Policy Framework
- D-MIMs and Context in Drools/plugin for Drools?
- Editor integration for policy authoring
- Context and conflict
  - Design time
  - Deployment time
  - Runtime identification
  - Runtime mitigation

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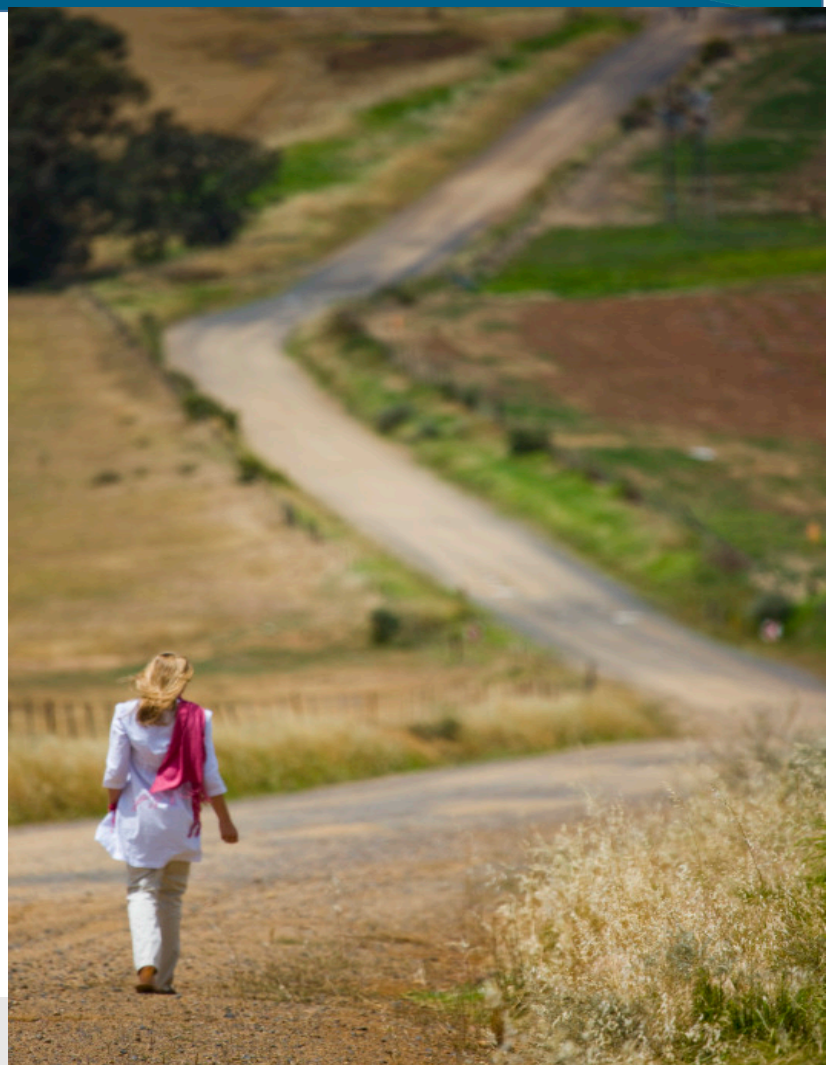
ADDENDUM:
SOME POLICY TERMINOLOGY



Policy & Engine

- *Policy* is an artefact that governs the choices in behaviour of a system
  - Separation of mechanism from policy
  - Has capabilities, defined in a specification, explicit / implicit trigger
  - Has multiple, partially relative, dimensions
  - Example for choices: in Network Management choices are operations on managed objects
- A *Policy Engine* is responsible for executing policies
  - Receiving triggers
  - Execute relevant policies
  - Receive actions from executed policies
  - Return / forward them
  - With all “-ities: scalability, performance, security, …

System & Application

- A *Policy System* controls and manages life cycle of policies
  - Functional and non-functional capabilities
  - Life cycle
    - Authoring
    - Deployment
    - Execution (using the engine)
- A *Policy Application* realizes a policy system
  - Builds / implements functional and non-functional capabilities

Policy Variants
Context-aware, Adaptive & Adaptable

Context-aware Policy

- makes different decisions based on context information
- static decision-making behavior
- *Fewer policies*: same trigger, different context

Policies are more flexible

Adaptable Policy

- Can change its decision making behavior
- Based on an external activity
  - outside the policy
- *Fewer policies*: same policy, multiple behaviors

Adaptive Policy

- Can change its decision making behavior
- Based on an internal activity
  - inside the policy
- *Fewer policies*: same policy, multiple behaviors
- *Policy can adapt* to target shifts

Policy Variants
Context-aware, Adaptive & Adaptable

Context-aware Policy

- Different trigger context results in different situations
- External context as part of situation or decision making can change decision
- Not understood context might signal shift in automation target

Adaptable Policy

- Non-context-aware
  - Set policy parameter
  - Set policy state logic
- Context-aware (trigger/external)
  - Based on context, set policy parameters and/or use different policy state logic

Adaptive Policy

- Change on automation target resulting in new/altered context
- Set policy parameter/state logic due to policy internal context
- Change state logic

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